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Amendments to the Claims:

Please amend the claims as follows:

1. (currently amended) A system for inspecting an object, the system comprising a work surface providing an object plane on which, in use, the object to be inspected is located; and a camera having a focal point and a field of vision, the camera being arranged with respect to the work surface so that at least part of the work surface is within the camera's field of vision, the camera being arranged to capture an image of the object, the image comprising a plurality of image data components, the system further including an apparatus for processing the object image, the apparatus being arranged to receive image data components from a single image of the object from the camera and to generate, using said image data components of said single image, three dimensional data representing at least part of the object, and wherein in order to generate said three dimensional data the apparatus is arranged to identify a plurality of said image data components that represent the position of a respective edge component of the object in an image plane, wherein, during the capture of said single image by the camera, the camera and the object are fixed with respect to one another, the processing apparatus being arranged to project each image edge data component onto the object plane to produce a respective object edge data component in the object plane, the processing apparatus being further arranged to determine whether each object edge data component relates to [[an]] a lower edge of the object that lies on the work surface or to an upper edge of the object that is offset above the work surface by an amount substantially equal to a thickness of the object at said upper edge, and wherein, upon determining that an only in respect of object edge data components that are determined to relate relates to an upper edge of the object that is offset above the work surface, the processing apparatus is arranged to adjust the value of the respective object edge data component by an amount depending on the ratio of the size of the said offset in a direction generally perpendicular with the work surface to the perpendicular distance of the camera's focal point from the object plane, such that said object edge data components that are determined to relate to an upper edge

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of the object are adjusted with respect to the other object data components produced by said processing apparatus from said single image.

2. (currently amended) A system as claimed in Claim 1, wherein when an edge profile of the object taken in a plane generally perpendicular to the object plane is generally perpendicular to the object plane, or is undercut, said object edge data components that are determined to relate to an upper edge of the object are [[is]] adjusted by subtracting an amount substantially equal to said ratio multiplied by the relative distance between the object edge data component and the position of the camera's focal point in the object plane.

3. (currently amended) A system as claimed in Claim 1, wherein when an edge profile of the object taken in a plane generally perpendicular to the object plane is beveled, the processing apparatus is arranged to determine if the angle of the beveled edge profile is greater than the angle made by a line of sight from the camera's focal point to said object edge data component and, upon so determining, to adjust said object edge data components that are determined to relate to an upper edge of the object by subtracting an amount substantially equal to said ratio multiplied by the relative distance between the object edge data component and the position of the camera's focal point in the object plane and by adding an amount substantially equal to the distance in the object plane between the edges of the beveled profile along said line of sight.

4. (currently amended) A system as claimed in Claim 1, wherein when an edge profile of the object taken in a plane generally perpendicular to the object plane is undercut and when the processing apparatus determines that an object edge data component relates to [[an]] a lower edge of the object that lies on the work surface, the processing apparatus is arranged to determine if the angle of the undercut edge profile is greater than the angle made by a line of sight from the camera's focal point to said object edge data component and, upon so determining, to adjust said object edge data component by an amount substantially equal to the distance in the object plane between the edges of the undercut profile along said line of sight.

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5. (currently amended) A system as claimed in Claim 1, wherein ~~the object has a first side facing the work surface and a second side facing the camera that is spaced apart from the first side, and~~ the processing apparatus is arranged to determines whether each ~~said~~ object edge data components relates to ~~[[an]]~~ a lower edge of the side of the object that lies on the work surface that faces the work surface or to an upper edge of the object that is offset above the work surface by an amount substantially equal to a thickness of the object at said upper edge on the side that faces the camera by calculating a respective first parameter relating to a notional reference line extending from the respective object edge data component, calculating a second parameter relating to a notional line extending between the respective object edge data component and a reference point in the object plane, and comparing the difference between said first parameter and said second parameter against a threshold value.

6. (currently amended) A system as claimed in Claim 5, wherein said first parameter comprises the value of an angle between an angle reference axis and said notional reference line extending from the respective object edge data component.

7. (currently amended) A system as claimed in Claim 5, wherein said second parameter comprises the value of an angle between the angle reference axis and said notional reference line extending between the respective object edge data component and said reference point.

8. (currently amended) A system as claimed in Claim 5, wherein said reference point on the object plane comprises the position of the camera's focal point in the object plane and said notional reference line extending from the respective object edge data component comprises a line normal to the object at said object edge data component, and wherein said threshold value is 90 degrees.

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9. (original) A system as claimed in Claim 1, wherein the processing apparatus is arranged to calculate a line of sight from the camera's focal point to the object edge data component and to determine the point at which the line of sight substantially meets the object edge, and to determine the amount of the offset depending on the location of said point.

10. (original) A system as claimed in Claim 9, wherein the line of sight lies in a plane substantially normal to the edge of the object at the location of the object edge data component.

11. (currently amended) An apparatus for processing an image, the apparatus being suitable for use in a system for inspecting an object, the system comprising a work surface providing an object plane on which, in use, the object to be inspected is located; and a camera having a focal point and a field of vision arranged with respect to the work surface so that at least part of the work surface is within the camera's field of vision, the camera being arranged to capture an image of the object, the image comprising a plurality of image data components, the apparatus being arranged to receive the image data components from the camera and to generate, using said image data components ~~from a single image without requiring the application of structured light to the object or the combination of data components from multiple images by triangulation~~, three dimensional data representing at least part of the object, and wherein in order to generate said three dimensional data ~~without requiring the application of structured light to the object or the combination of data components from multiple images by triangulation~~ the apparatus is arranged to identify a plurality of said image data components that represent the position of a respective edge component of the object in an image plane, wherein, ~~during the capture of an image by the camera, the camera and the object are fixed with respect to one another~~, the processing apparatus being arranged to project each image edge data component onto the object plane to produce a respective object edge data component in the object plane, the processing apparatus being further arranged to determine whether each said object edge data components relates to [[an]] a lower edge of the object that lies on the work surface or to an upper edge of the object that is offset above the work surface by calculating a respective first parameter relating to a notional reference

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line extending from the respective object edge data component, calculating a second parameter relating to a notional line extending between the respective object edge data component and a reference point in the object plane, and comparing the difference between said first parameter and said second parameter against a threshold value, and dependent on the outcome of said comparison, to determine that said respective object edge data component relates to a lower edge or an upper edge of said object, wherein and, upon determining that an object edge data component relates to an upper edge of the object, the processing apparatus is arranged that is offset above the work surface; to adjust the value of the object edge data component by an amount depending on the ratio of the size of the offset in a direction generally perpendicular with the work surface to the perpendicular distance of the camera's focal point from the object plane.

12. (currently amended) A method of processing an object image in a system for inspecting an object, the system comprising a work surface providing an object plane on which, in use, the object to be inspected is located; and a camera having a focal point and a field of vision arranged with respect to the work surface so that at least part of the work surface is within the camera's field of vision, the camera being arranged to capture an image of the object, the image comprising a plurality of image data components, and wherein, during the capture of an image by the camera, the camera and the object are fixed with respect to one another, the method comprising receiving the image data components from the camera for a single image of the object; generating, using said image data components of the single image, three dimensional data representing at least part of the object; identifying a plurality of said image data components that represent the position of a respective edge component of the object in an image plane; projecting each image edge data component onto the object plane to produce a respective object edge data component in the object plane; determining whether each object edge data component relates to [[an]] a lower edge of the object that lies on the work surface or to an upper edge of the object that is offset above the work surface by an amount substantially equal to a thickness of the object at said upper edge; and, upon determining that an only in respect of object edge data components that are determined to relates to an upper edge of the object that is offset above the work surface,

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adjusting the value of the respective object edge data component by an amount depending on the ratio of the size of the said offset in a direction generally perpendicular with the work surface to the perpendicular distance of the camera's focal point from the object plane, such that said object edge data components that are determined to relate to an upper edge of the object are adjusted with respect to the other object data components produced by said processing apparatus from said single image.

13. (original) A computer program product comprising computer usable code for causing a computer to perform the method of Claim 12.

14. (previously presented) A system as claimed in claim 1, wherein said object is substantially planar and has a substantially constant thickness, said processing apparatus being arranged to combine said object edge data components with a data component representing said thickness in order to generate said three dimensional data representing said object.

15. (cancelled)

16. (new) A system as claimed in claim 5, wherein the processing apparatus is arranged to determine whether said object edge data points represent an interior perimeter of said object or an exterior perimeter of said object, and to arrange said object edge data points into sets in which each object edge data point in a respective set represents a common interior or exterior perimeter, and wherein the processing apparatus determines whether at least one object edge data component in each set relates to a lower edge of the object or to an upper edge of the object.

17. (new) An apparatus as claimed in claim 11, wherein the processing apparatus is arranged to determine whether said object edge data points represent an interior perimeter of said object or an exterior perimeter of said object, and to arrange said object edge data points into sets in which each object edge data point in a respective set represents a common interior or exterior perimeter,

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and wherein the processing apparatus determines whether at least one object edge data component in each set relates to a lower edge of the object or to an upper edge of the object.